

Position-Dependent Mass Quantum systems and ADM formalism

Davood J. Momeni

Sultan Qaboos University & North-West University

International Conference on Holography, String Theory and Discrete Approaches in Hanoi

6 August 2020

Contents

- Introduction
- Super Mass Tensor for GR as PDM classical system
- Super phase space
- Reduction of the Einstein Field Equations (EFE) to Hamilton's equation via covariant Hamiltonian
- Quantization of GR
- Quantum cosmology
- Note about ADM decomposition formalism and reduced phase space
- Final remarks

Introduction

- Classical mechanics is Galilean invariant, i.e, time parameter t and position coordinate $q(t)$ are explicitly functions of each other.
- Non existence of a locally Lorentz invariant quantum theory with single particle interpretation.
- In GR, we have difficulty to interpret time as we did in classical mechanics.
- GR is locally Lorentz invariant (time t is just a coordinate and is no longer considered as a parameter).
- In the language of the variational calculus, the analogue to coordinate $q(t)$ is the Riemannian metric $g_{ab}(x^c)$, , $a, b = 0...3$ is a function of the all coordinates $x^c = (t, x^A), A = 1,..3$.

Introduction

- That makes quantum gravity difficult to build. Basically we have several QGs,
- Semiclassical quantum gravity (quantum fields on classical backgrounds)
- Loop Quantum gravity
- String Theory
- Non commutativity as a way to address quantum effects in gravity (singularities,..)
- Lorentz symmetry breaking (Lifshitz theories(stochastically renormalizable),..)
- It seems we have the problem of “disappearance of time”(Timeless quantum gravity)

Introduction

we are still looking for a fully covariant canonical quantum theory for gravity!

- My observations initiated when I studied GR as a classical gauge theory [M. Carmeli, "Classical fields: General Relativity and Gauge Theory" (1982)]
- During studying non standard classical dynamical systems I found a class of Lagrangian models with second order time derivative of the position $L(q, \dot{q}, \ddot{q})$.
- A wide class of such models reduce to the position dependence mass (PDM) models[1507.05217, 1605.06829, 1710.02135].
- It is obviously interesting to show that whether GR reduces to such models!.
- The classical Einstein-Hilbert (EH) Lagrangian reduces to the position-dependent -mass (PDM) model up to a boundary term.

Introduction

Analogy between classical mechanics and GR

- GR respects gauge transformations (any type of arbitrary change in the coordinates, from one frame to the other $x^a \rightarrow \tilde{x}^a$)
- We can rewrite EH Lagrangian in terms of the metric, first and second derivatives of it. It looks like a classical system in the form of $L(q, \dot{q}, \ddot{q})$.
- In this formal analogy, the classical acceleration term $\ddot{q}$ in the classical models under study is now replaced with the second derivative for metric i.e., $\partial_e \Gamma_{dab}$.
- we will need to define a super mass tensor as a function of the metric instead of the common variable mass function $m(q(t))$ in classical mechanic.

Introduction

Analogy between classical mechanics and GR

Theory	Position	Velocity	Acceleration	Mass
Classical Mechanics with PDM	$q(t)$	$\dot{q}(t)$	$\ddot{q}(t)$	Scalar mass $m(q(t))$
GR	g_{ab}	$\partial_d g_{ab}$	$\partial_e \partial_d g_{ab}$	M^{abldeh}

Introduction

- The notation for Einstein-Hilbert action is: $S_{EH} = \int d^4x \mathcal{L}_{GR}$
- Here $\mathcal{L}_{GR} = \mathcal{L}_{GR}(|g|, \partial|g|, g, \bar{g}, \partial g, \partial \bar{g})$
- Notations: $g \equiv g_{ab}$,
 $\bar{g} \equiv g^{ab}$, $|g| \equiv \det(g_{ab}) = \frac{1}{\det(\bar{g})}$, $\frac{1}{2} \bar{g} \cdot \partial g \equiv \Gamma_{bc}^a$, $\partial g = \Gamma_{bla} \equiv g_{bl,a} + g_{la,b} - g_{ba,l}$.
- We adopt metricity condition $\nabla_a g^{bc} = |g|^{-1/2} \partial_a (|g|^{1/2} g^{bc}) \equiv |g|^{-1/2} \partial (|g|^{1/2} \bar{g}) = 0$ along $\partial \cdot \bar{g} = -\bar{g} \cdot \partial g \cdot \bar{g}$.
- I showed that GR Lagrangian reduces to a PDM fully classical system with a super mass tensor of rank six.
- I built a consistent super phase space as well as a set of Poisson brackets.
- I show that gravitational field equations reduced to a set of first order Hamilton's equations.

Super Mass Tensor for GR as PDM classical system

Equivalent form for Lagrangian of the GR

- One can eliminate the second derivative term $\partial_{de}g_{ab}$ simply by integrating by part and using the metricity condition $\nabla_a g^{bc} = 0$, by taking into the account all the above requirements a possible:

$$\mathcal{L}_{GR} = \frac{1}{2}\sqrt{|g|} \left(g^{al}g^{be}\Gamma_{bla}\partial^h g_{eh} + g^{be}g^{dh}\Gamma_{bld}\partial^l g_{eh} + \frac{1}{2}g^{al}g^{bd}g^{te}\Gamma_{ild}\Gamma_{bea} - \frac{1}{2}g^{al}g^{bd}g^{te}\Gamma_{ila}\Gamma_{bed} \right) \text{ and we have } S_{EH} = \int d^4x \mathcal{L}_{GR} + B.T$$

- By B.T we mean boundary term defined as:

$$B.T = \int_{\partial\mathcal{M}} \sqrt{|h_{AB}|} h^{BD} h^{AL} \Gamma_{BLA} |_{x^D=\text{constant}} + \int_{\partial\mathcal{M}} \sqrt{|h_{AB}|} h^{BD} h^{AL} \Gamma_{BLD} |_{x^A=\text{constant}}$$

- We can re express the above GR Lagrangian in our convenient notations as:

$$\mathcal{L}_{GR} = \frac{1}{2}\sqrt{|g|} \left(\bar{g} \cdot \partial g \cdot \bar{g} \cdot \bar{\partial} g + \bar{g} \cdot \bar{g} \cdot \partial g \cdot \bar{\partial} g + \frac{1}{2} \bar{g} \cdot \bar{g} \cdot \bar{g} \cdot \partial g \cdot \partial g - \frac{1}{2} \bar{g} \cdot \partial g \cdot \bar{g} \cdot \bar{g} \cdot \partial g \right)$$

- Note that by "dot" we mean tensor product (we adopt Einstein summation rule).

Super Mass Tensor for GR as PDM classical system

- From the above representation we can realize $\{g, \bar{g}\}$ as two fields , in analogy to the Dirac Lagrangian where the fermionic pairs $\psi, \bar{\psi}$ appeared .
- The difference here is due to the fact that the pair of objects $\{g, \bar{g}\}$ depend on each other as we know $g \cdot \bar{g} = \delta$, the Kronecker delta, however in the Dirac Lagrangian the norm $\bar{\psi}\psi \neq I$.
- In our program we won't use this duality and we will focus on the coordinates representation of the GR Lagrangian.
- If we substitute the definition of Gamma terms and combine the theory, we obtain the final form for the Lagrangian as a PDM system for coordinate g_{ab} :

$$\mathcal{L}_{GR} = \frac{1}{2} \sqrt{|g|} M^{abld eh} \partial_a g_{bl} \partial_d g_{eh}$$

Super Mass Tensor for GR as PDM classical system

Definition of super mass tensor:

$$\begin{aligned} |g|^{1/2} \overline{M} &= |g|^{1/2} M^{a_1 b_1 l_1 d_1 e_1 h_1} = \frac{1}{4} g^{al} g^{bd} g^{te} \times \\ &\left(\delta_a^{a_1} \delta_b^{b_1} \delta_e^{l_1} + \delta_a^{b_1} \delta_b^{a_1} \delta_e^{l_1} - \delta_a^{l_1} \delta_b^{b_1} \delta_e^{a_1} \right) \left(\delta_d^{d_1} \delta_l^{h_1} \delta_t^{e_1} - \delta_d^{h_1} \delta_l^{d_1} \delta_t^{e_1} + \delta_d^{e_1} \delta_l^{h_1} \delta_t^{d_1} \right) \\ &- \frac{1}{4} g^{al} g^{bd} g^{te} \left(\delta_b^{a_1} \delta_d^{b_1} \delta_e^{l_1} + \delta_b^{b_1} \delta_d^{a_1} \delta_e^{l_1} - \delta_b^{l_1} \delta_d^{b_1} \delta_e^{a_1} \right) \left(\delta_a^{d_1} \delta_l^{h_1} \delta_t^{e_1} - \delta_a^{h_1} \delta_l^{d_1} \delta_t^{e_1} + \delta_a^{e_1} \delta_l^{h_1} \delta_t^{d_1} \right) \\ &+ \frac{1}{4} g^{al} g^{bd} g^{te} \left(\delta_a^{d_1} \delta_b^{e_1} \delta_e^{h_1} + \delta_a^{e_1} \delta_b^{d_1} \delta_e^{h_1} - \delta_a^{h_1} \delta_b^{e_1} \delta_e^{d_1} \right) \left(\delta_d^{a_1} \delta_l^{l_1} \delta_t^{b_1} - \delta_d^{l_1} \delta_l^{a_1} \delta_t^{b_1} + \delta_d^{b_1} \delta_l^{l_1} \delta_t^{a_1} \right) \\ &- \frac{1}{4} g^{al} g^{bd} g^{te} \left(\delta_b^{d_1} \delta_d^{e_1} \delta_e^{h_1} + \delta_b^{e_1} \delta_d^{d_1} \delta_e^{h_1} - \delta_b^{h_1} \delta_d^{e_1} \delta_e^{d_1} \right) \left(\delta_a^{a_1} \delta_l^{l_1} \delta_t^{b_1} - \delta_a^{l_1} \delta_l^{a_1} \delta_t^{b_1} + \delta_a^{b_1} \delta_l^{l_1} \delta_t^{a_1} \right) \\ &+ g^{al} \delta_a^{d_1} g^{be} g^{dh} \delta_e^{e_1} \delta_h^{h_1} \left(\delta_b^{b_1} \delta_d^{a_1} \delta_l^{l_1} + \delta_b^{a_1} \delta_d^{l_1} \delta_l^{b_1} - \delta_b^{b_1} \delta_d^{l_1} \delta_l^{a_1} \right) \\ &+ g^{al} g^{be} g^{dh} \delta_d^{d_1} \delta_e^{e_1} \delta_h^{h_1} \left(\delta_a^{a_1} \delta_b^{b_1} \delta_l^{l_1} + \delta_a^{l_1} \delta_b^{a_1} \delta_l^{b_1} - \delta_a^{l_1} \delta_b^{b_1} \delta_l^{a_1} \right) \\ &+ g^{al} \delta_a^{a_1} g^{be} g^{dh} \delta_e^{b_1} \delta_h^{l_1} \left(\delta_b^{e_1} \delta_d^{d_1} \delta_l^{h_1} + \delta_b^{d_1} \delta_d^{h_1} \delta_l^{e_1} - \delta_b^{e_1} \delta_d^{h_1} \delta_l^{d_1} \right) \\ &+ g^{al} g^{be} g^{dh} \delta_d^{a_1} \delta_e^{b_1} \delta_h^{l_1} \left(\delta_a^{d_1} \delta_b^{e_1} \delta_l^{h_1} + \delta_a^{h_1} \delta_b^{d_1} \delta_l^{e_1} - \delta_a^{h_1} \delta_b^{e_1} \delta_l^{d_1} \right). \end{aligned}$$

Super Mass Tensor for GR as PDM classical system

Having the Lagrangian of GR, one can define a canonical pair of position conjugate momentum $(g, \bar{p})$ and construct a phase space.

Super phase space

- Defining the super conjugate momentum tensor :

$$p^{rst} = \frac{\partial \mathcal{L}_{GR}}{\partial(\partial_r g_{st})} = \frac{\sqrt{g}}{2} \left(M^{rstdeh} \partial_d g_{eh} + M^{ablrst} \partial_a g_{bl} \right)$$

- Note that for the mass tensor $M^{rstdeh} \partial_d g_{eh} = M^{ablrst} \partial_a g_{bl}$.

- A possible classical Hamiltonian: $\mathcal{H}_{GR} = \frac{1}{2\sqrt{|g|}} M^{abldeh} M_{rstabl} p^{rst} M_{uvwdeh} p^{uvw}$

- A possible Poisson's bracket $\{F, G\}_{P.B}$ adopted to this system is:

$$\{F(g_{mn}, p^{stu}), G(g_{mn}, p^{stu})\}_{P.B} = \sum \left(\frac{\partial F}{\partial g_{ab}} \frac{\partial G}{\partial p^{rst}} - \frac{\partial F}{\partial p^{rst}} \frac{\partial G}{\partial g_{ab}} \right)$$

- In our notation it simplifies to the following expression

$$\{F(g, \bar{p}), G(g, \bar{p})\}_{P.B} = \sum \left(\frac{\partial F}{\partial g} \frac{\partial G}{\partial \bar{p}} - \frac{\partial F}{\partial \bar{p}} \frac{\partial G}{\partial g} \right)$$

- For our super phase coordinates (g_{ab}, p^{rst}) , I postulate that $\{g_{ab}, p^{rst}\}_{P.B} = c^r \delta_{ab}^{rs}$

Super phase space

- Here δ_{ab}^{rst} is the generalized Kronecker defined as $\delta_{ab}^{rst} = 2! \delta_{[a}^s \delta_{b]}^t$.
- In the above Poisson's bracket, with structure constants c^r provide a classical minimal volume for super phase space (zero for Poisson's bracket same objects).
- We have now full algebraic structures in the super phase space and canonical Hamiltonian.
- We can write down Hamilton's equations as first order reductions of the Euler-Lagrange equations derived from the Lagrangian .
- I will show that how Einstein equation reduces to a type of covariant Hamilton equations.

Reduction of the Einstein Field Equations (EFE) to Hamilton's equation via covariant Hamiltonian

- The set of Hamilton's equations derived from the Hamiltonian $\partial_a g_{bl} = \{g_{bl}, \mathcal{H}_{GR}\}_{P.B} = \frac{\partial \mathcal{H}_{GR}}{\partial p^{abl}}$,

$$\partial_a p^{abl} = \{p^{abl}, \mathcal{H}_{GR}\}_{P.B} = - \frac{\partial \mathcal{H}_{GR}}{\partial g_{bl}}$$

- We explicitly can write this pair of Hamilton's equation given as follows:

$$\frac{2}{\sqrt{g}} \partial_a g_{bl} = M^{a'b'l'deh} M_{rsta'b'l'} M_{uvwdeh} \left(\delta_a^u \delta_b^v \delta_l^w p^{rst} + \delta_a^r \delta_b^s \delta_l^t p^{uvw} \right)$$

$$\begin{aligned} -\frac{2}{\sqrt{g}} \partial_a p^{abl} &= M^{a'b'l'deh} p^{rst} M_{rsta'b'l'} p^{uvw} \frac{\partial M_{uvwdeh}}{\partial g_{bl}} + M^{a'b'l'deh} p^{rst} M_{uvwdeh} \frac{\partial M_{rsta'b'l'}}{\partial g_{bl}} \\ &+ \frac{\partial M_{a'b'l'deh}}{\partial g_{bl}} p^{rst} M_{rsta'b'l'} p^{uvw} M_{uvwdeh} + M^{a'b'l'deh} \frac{\partial p^{rst}}{\partial g_{bl}} M_{rsta'b'l'} p^{uvw} M_{uvwdeh} \\ &+ M^{a'b'l'deh} p^{rst} M_{rsta'b'l'} \frac{\partial p^{uvw}}{\partial g_{bl}} M_{uvwdeh}. \end{aligned}$$

- I believe that one can integrate this system as a general non autonomous dynamical system .

Quantization of GR

- I'm going to define appropriate forms for Dirac brackets:

$$\hat{\pi}^{rst} \equiv -i\hbar^r \frac{\partial}{\partial \hat{g}_{st}}, \left[\hat{g}_{ab}, \hat{\pi}^{rst} \right] = i\hbar^r \delta_{ab}^{st}$$

- The classical phase space spanned by the (g_{ab}, p^{rst}) one has more degrees of freedom (dof), basically is $10^5 (= 10 \times 10^4)$ dimensional for a Riemannian manifold.
- The Dirac constant $\hbar$ is proportional to the minimum volume of the phase space V_0 defined as $\omega_0 = \int D(g_{ab}, p^{rst})$ is a covariant volume element.
- The super mass tensor $\bar{M} = M^{abldelh}$ is a homogeneous (order 6) of the metric tensor

Quantization of GR

- Using the formalism of quantization for PDM systems the canonical quantized Hamiltonian for GR is:
$$\hat{\mathcal{H}}_{GR}(\hat{g}_{ab}, \frac{\partial}{\partial \hat{g}_{st}}) = -\frac{1}{2} f_{rstuvw}^{1/2} \hbar^r \frac{\partial}{\partial \hat{g}_{st}} \left[f_{rstuvw}^{1/2} \hbar^u \frac{\partial}{\partial \hat{g}_{vw}} \right]$$
 here the auxiliary, scaled super mass tensor f_{rstuvw} is
$$f_{rstuvw} \equiv |g|^{-1/4} M^{abldeh} M_{rstabl} M_{uvwdeh}.$$
- It is adequate to write the quantum Hamiltonian in the following closed form:
$$\hat{\mathcal{H}}_{GR}(\hat{g}_{ab}, \hat{\pi}^{mnp}) = \frac{1}{2} \left[|g|^{-1/2} \bar{M} M M \right]^{1/2} \bar{\pi} \left[|g|^{-1/2} \bar{M} M M \right]^{1/2} \bar{\pi}$$
 where $\bar{\pi}$ is contravariant component of the super momentum π , etc.
- The above quantization of Hamiltonian is covariant since we didn't specify time t from the other spatial coordinates x^A .

Quantization of GR

- The model is considered as a timeless model, i.e, there is no first order time derivative in the final wave equation like $\frac{\partial}{\partial t}$.
- The associated functional second order wave equation which is fully locally Lorentz invariant as well as general covariant:
$$-\frac{1}{2}f_{rstuvw}^{1/2}\hbar^r\frac{\partial}{\partial\hat{g}_{st}}\left[f_{rstuvw}^{1/2}\hbar^u\frac{\partial}{\partial\hat{g}_{vw}}\Psi(\hat{g}_{ab})\right]=E\Psi(\hat{g}_{ab})$$
- In our suggested functional wave equation for $\Psi(\hat{g}_{ab})$, we end up by the covariant (no first order derivative) of the functional Hilbert space.
- This model is a subclass of the timeless models of QG

Quantum cosmology

- We consider flat, Friedmann-Lemaître-Robertson-Walker (FLRW) model with Lorentzian metric $g_{ab} = \text{diag}(1, -a(t)\Sigma_3)$ where Σ_3 is the unit metric tensor for flat space, in coordinates $x^a = (t, x, y, z)$.
- The non vanishing elements of the super mass tensor:

$$M^{abldeh} = -12a^{-2}\delta^{a0}\delta^{d0}\delta^{BL}\delta^{EH}, B, L, E, H = 1, 2, 3$$
- The auxiliary scaled super mass tensor $f_{rstuvw} = -\frac{3a^{1/2}}{4}\delta_{u0}\delta_{r0}\delta_{VW}\delta_{ST}$
- The functional wave equation reduces to the hypersurfaces Σ_3 coordinates $X^A = (x, y, z)$:

$$\frac{3\hbar_0^2 a^{1/2}}{8} \frac{\partial^2 \Psi(\hat{g}_{AB})}{\partial \hat{g}_{SS} \partial g_{VV}} = E \Psi(\hat{g}_{AB})$$

Quantum cosmology

- it reduces simply to the following ordinary differential equation

$$a\Psi''(a) - \Psi'(a) - \frac{32Ea^{5/2}}{3h_0^2}\Psi(a) = 0$$

- It can be reduce to a standard second order differential equation for wave function

$$\Psi(a) = \sqrt{a}\phi(a), \phi''(a) - \left(\frac{32Ea^{1/2}}{3h_0^2} + \frac{3}{4a^2}\right)\phi(a) = 0.$$

- There are exact solutions for asymptotic regimes:

$$a^{3/2} \text{ if } a \rightarrow 0, \exp\left[\frac{16\sqrt{2E}}{5\sqrt{3}h_0}a^{5/4}\right] \text{ if } a \rightarrow \infty.$$

- By suggesting $\phi(a) = \zeta(a)a^{3/2} \exp\left[\frac{16\sqrt{2E}}{5\sqrt{3}h_0}a^{5/4}\right]$ and $\zeta(a)$ will come as a transcendental (hypergeometric) function.

Quantum cosmology

Complete wave function:

$$\bullet \quad \Psi(a) = a^{5/2} \exp\left[\frac{16\sqrt{2E}}{5\sqrt{3}\hbar}a^{5/4}\right] \frac{3^{2/5}\hbar^{4/5}e^{-\frac{2}{15}\left(\frac{8\sqrt{6}ea^{5/4}}{\hbar}+3\right)}\left(5c_1\Gamma\left(\frac{1}{5}\right)I_{-\frac{4}{5}}\left(\frac{16\sqrt{\frac{2e}{3}}a^{5/4}}{5\hbar}\right)+32\sqrt[5]{2}c_2\Gamma\left(\frac{4}{5}\right)I_{\frac{4}{5}}\left(\frac{16\sqrt{\frac{2e}{3}}a^{5/4}}{5\hbar}\right)\right)}{64\sqrt[5]{5}a}$$

The eigenvalue E (positive, negative or zero) can be discrete as well as continuous (bound states for $E < 0$).

- Remarkable is for vanishing energy state, $E = 0$
 $\Psi(a) = N_0 + Na^2$.

Note about ADM decomposition formalism and reduced phase space

- In our formalism If one adopt the ADM decomposition of the metric g_{ab} as follows

$$ds^2 = g_{ab}dx^a dx^b = h_{AB}dx^A dx^B + 2N_A dx^A dx^0 + (-N^2 + h^{AB}N_A N_B)(dx^0)^2$$

here x^0 is time, $A, B = 1, 2, 3$ refer to the spatial coordinates and h_{AB} is spatial metric, we recall the super conjugate momentum

$$\pi^{rs} = \frac{\partial \mathcal{L}_{GR}}{\partial \dot{g}_{st}} = \frac{\sqrt{g}}{2} \left(M^{0stdeh} \partial_d g_{eh} + M^{abl0st} \partial_a g_{bl} \right)$$

Building the Hamiltonian in a standard format as:

$$\mathcal{H}_{GR}^{ADM} = \frac{1}{2\sqrt{|g|}} M^{abldeh} M_{0stabl} \pi^{st} M_{0vwdeh} \pi^{vw}$$

- Again we can recover ADM Hamiltonian!

Final remarks

- The canonical covariant quantization which I proposed here is a consistent theory.
- The GR action in a suitable form the Lagrangian reduced to a purely kinetic theory with position dependence mass term.
- With such a simple quadratic Lagrangian, I defined a conjugate momentum corresponding to the metric tensor.
- I developed a classical Hamiltonian using the metric and its conjugate momentum.
- One can write classical Hamilton's equations for metric and momentum are analogous to the second order nonlinear Einstein field equations.
- We replaced Poisson's brackets with Moyal(Dirac) and we defined a quantum Hamiltonian for GR.

Final remarks

- I notice here that even if we didn't remove second derivative terms using integration part by part, it was possible to define a second conjugate

momentum: $r^{abcd} = \frac{\partial \mathcal{L}_{GR}}{\partial(\partial_a \partial_b g_{cd})}$.

- If we impose a Bianchi identity between $(g_{ab}, p^{rst}, r^{abcd})$, it is possible to fix this new momentum in terms of the other one and the metric.
- with the Bianchi identity,

$$\{g_{ab}, \{p^{cde}, r^{fghi}\}_{P.B}\}_{P.B} + \{p^{cde}, \{r^{fghi}, g_{ab}\}_{P.B}\}_{P.B} + \{r^{fghi}, \{g_{ab}, p^{cde}\}_{P.B}\}_{P.B} = 0$$
- A suitable Legendre transformation from the GR Lagrangian

$$\mathcal{H}_{GR} = p^{rst} \partial_r g_{st} + r^{abcd} (\partial_a \partial_b g_{cd}) - \mathcal{L}_{GR}$$
- One obtains a standard Hamiltonian without this new higher order momentum.

THANK YOU !

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